Analysis Of Reaction Diffusion Problems Using Differential Quadrature Method

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Abstract-- In this paper, a hybrid technique of differential quadrature method and Runge-Kutta fourth order method is employed to analyze reaction-diffusion problems. The obtained results are compared with the available analytical ones. Further, a parametric study is introduced to investigate the influence of reaction and diffusion characteristics on behavior of the obtained results.

Index Term-- Reaction-diffusion, Differential Quadrature, Runge-Kutta.

1. INTRODUCTION

Reaction-diffusion problems frequently arise in engineering, chemical, medical and biological systems. Thermal wave propagation, Fisher and FitzHugh-Nagumo are some models for such problems. Thermal wave physics play an ever-increasing role in the study of material parameters. It has been employed in optical investigations of solids, liquids, and gases with photo-acoustic and thermal lens spectroscopy. Thermal waves have also been used to analyze the thermal and thermodynamic properties of materials and for imaging thermal and material features within a solid sample [1]. Fisher model plays an important role in the spatial spread of gene in population [2]. FitzHugh-Nagumo model can be applied to investigate behavior of heart, excitable cells and muscles [3].

Reaction–diffusion problems have been extensively solved using various techniques. Due to the nonlinearity and complexity of such problems, only limited cases can analytically be solved [4-7]. Yan applied the projective Riccati equation method to solve Schrodinger equation in nonlinear optical fibers [4]. Then Mei, Zhang and Jiang employed the same method to get the exact solutions for some reaction-diffusion problems [5]. Abdusalam applied a factorization technique to find exact traveling wave solutions [6]. Zhaosheng employed Lie technique to solve fisher model in terms of elliptic functions [7]. Literature on the numerical solution of reaction–diffusion equations is sparse; David, Curtis and John introduced time integration methods to solve thermal wave propagation [8]. Marcus applied Finite difference method to study the dynamics of predator–prey interactions [9]. As well as, Chen et al. employed the finite element method to solve advective reaction-diffusion equations [10]. Then Christos et al. applied also the same method to solve the problem with boundary layers [11]. Recently differential quadrature method has been efficiently employed in a variety of engineering problems [12]. Meral and Sezgin used this method and finite difference method with a relaxation parameter to solve nonlinear reaction-diffusion equation in one and two dimensions [13]. Moreover, Meral applied differential quadrature method and implicit Euler method to solve density dependent nonlinear reaction-diffusion equation [14]. Wu and Liu have been introduced the generalization of the differential quadrature method to solve linear and non linear differential equations [15].

In spite of all these efforts, analysis of Reaction–diffusion problems is still of significant interests. This research employs a hybrid technique of differential quadrature method (DQM) and Runge-Kutta fourth order method (RK4) for solving reaction-diffusion problems. The obtained results are compared with the previous analytical ones. Furthermore, a parametric study is introduced to investigate the effect of reaction and diffusion parameters on behavior of the obtained results.

2. NUMERICAL PROCEDURE

The main strategy is to employ DQM to reduce the problem to a system of ordinary differential equations then to apply RK4 to solve the reduced system as follows:

2.1. Thermal wave propagation

Propagation of thermal waves through a rectangular plate, is governed by [16]:

\[ \frac{\partial U}{\partial t} = \alpha \frac{\partial^2 U}{\partial x^2} + \beta \frac{\partial^2 U}{\partial y^2} + \frac{\gamma}{\delta} (U - U_0)^2, \text{ } t > 0, \text{ } (0,0) < (x,y) < (a,b) \]

(1)

Where: \( U \) is a temperature, \( \alpha \) and \( \beta \) are diffusion parameters in direction of \( x \) and \( y \), respectively, \( \gamma \) and \( \delta \) are reaction parameters, \( a \) and \( b \) are plate dimensions in direction of \( x \) and \( y \), respectively and \( U_0 \) is a maximum temperature of the system.

Along the external boundaries, the temperatures can be described as:

\[ a_1 U (a,y,t) + b_1 \frac{\partial U}{\partial x} \bigg|_{(0,y,t)} = f_1(y,t) \]  

(2-a)

\[ a_2 U (a,y,t) + b_2 \frac{\partial U}{\partial x} \bigg|_{(a,y,t)} = f_2(y,t) \]  

(2-b)
\[ a_j U(x,0,t) + b_j \frac{\partial U}{\partial y}(x,0,t) = f_j(x,t) \quad (2-c) \]
\[ a_j U(x,b,t) + b_j \frac{\partial U}{\partial y}(x,b,t) = f_j(x,t) \quad (2-d) \]

Where \( a_j, b_j \) and \( f_j, (i = 1,4) \), are known functions.

The initial temperature may be described as:
\[ U(x,y,0) = g(x,y) \quad (3) \]
where \( g(x,y) \) is a known function.

Solution of Eqs.(1), (2) and (3) can be obtained as follows:
1- Discretize the spatial domain using Chebyshev-Gauss-Lobatto grid points[12], such as:
\[ x_i = \frac{a}{2} \left[ 1 - \cos \left( \frac{(i-1)\pi}{N-1} \right) \right], \quad i = 1,2,\cdots,N \quad (4-a) \]
\[ y_j = \frac{b}{2} \left[ 1 - \cos \left( \frac{(j-1)\pi}{M-1} \right) \right], \quad j = 1,2,\cdots,M \quad (4-b) \]

2- Apply the method of differential quadrature in terms of nodal temperature, such that:
\[ \frac{\partial U}{\partial x}(x_i,y_j,t) = \sum_{k=1}^{N} A_{ik} U(x_k,y_j,t) \quad (5-a) \]
\[ \frac{\partial U}{\partial y}(x_i,y_j,t) = \sum_{l=1}^{M} A_{il} U(x_i,y_l,t) \quad (5-b) \]
\[ \frac{\partial^2 U}{\partial x^2}(x_i,y_j,t) = \sum_{k=1}^{N} B_{ikk} U(x_k,y_j,t) \quad (5-c) \]
\[ \frac{\partial^2 U}{\partial y^2}(x_i,y_j,t) = \sum_{l=1}^{M} B_{ll} U(x_i,y_l,t) \quad (5-d) \]

Where \( A_{ik} \) and \( B_{ij} \) \( (p = x, y) \) are the first and second order weighting coefficients with respect to \( p \)[12].

3- On sustainable substitution from Eqs. (5) into (1), one can reduce the problem to the following system of ordinary differential equations as:
\[ \frac{dU}{dt}(x_i,y_j,t) = q_0 \left[ U(x_1,y_1,t),U(x_2,y_1,t),\cdots,U(x_N,y_M,t) \right] \]

Or simply
\[ \frac{dU}{dt}(x_i,y_j,t) = q_0 (U_{11},U_{21},\cdots,U_{NM},t), \quad i = 1,N \text{ and } j = 1,M. \quad (6) \]

Where
\[ q_0 = \alpha \sum_{i=1}^{N} B_{ii} U(x_i,y_i,t) + \beta \sum_{i=1}^{M} B_{ii} U(x_i,y_i,t) + \gamma (U_0 - U_0) \]
\[ a_i = 1, N \text{ and } j = 1, M. \quad (7) \]

4- Update the temperature using RK4 such that [17]:
\[ U(x_i,y_j,t_0 + \Delta t) = U(x_i,y_j,t_0) + \frac{\Delta t}{6} \left[ H_i^0 + 2H_i^0 + 2H_i^0 + H_i^0 \right] \]

Where
\[ H_i^0 = \Delta q_j (U_{11} + \frac{H_i^0}{2},U_{21} + \frac{H_i^0}{2},\cdots,U_{NM} + \frac{H_i^0}{2},t_0 + \Delta t) \]
\[ H_i^0 = \Delta q_j (U_{11} + \frac{H_i^0}{2},U_{21} + \frac{H_i^0}{2},\cdots,U_{NM} + \frac{H_i^0}{2},t_0 + \Delta t) \]
\[ H_i^0 = \Delta q_j (U_{11} + \frac{H_i^0}{2},U_{21} + \frac{H_i^0}{2},\cdots,U_{NM} + \frac{H_i^0}{2},t_0 + \Delta t) \]

Where \( \Delta t = t_1 - t_0 = t_2 - t_1 = \cdots = t_p - t_{p-1} \)

2.2. Fisher model
This model suggests that population density is governed by [18]:
\[ \frac{\partial U}{\partial t} = D \frac{\partial^2 U}{\partial x^2} + \gamma U (U_0 - U), \quad t > 0, \quad 0 < x < a \]

Where: \( U(x,t) \) is the population density, \( t \) and \( x \) are time and location respectively, \( U_0 \) is a maximum population density, \( \gamma \) is the reaction factor defining the migration rate and \( D \) is the diffusion coefficient defining the reproduction rate.

The boundary and initial conditions of such model may be also described as:
\[ a U(0,t) + b \frac{\partial U}{\partial x}(0,t) = f_1(t) \quad (11-a) \]
\[ a U(a,t) + b \frac{\partial U}{\partial x}(a,t) = f_2(t) \quad (11-b) \]

Where \( a_1, b_1 \) and \( f_1, (i = 1,2) \), are known functions.

The initial temperature can be described as:
\[ U(x,0) = g(x) \]

Where \( g(x) \) is a known function.
The proposed technique can be applied to reduce Eqs. (10), (11) and (12) to the following system of ODEs:

$$\frac{dU_j}{dt} = D \sum_{j=1}^{N} B_{ij}U_{(x_{j-1},0)} + \gamma U_{(x_{j-1})}[U_{(0-0)} - U_{(x_{j-1})}], \quad i = 1,2,\ldots,N$$  \hspace{1cm} (13)

Where $B_{ij}$, (i, j = 1, N) are previously defined through Eqs.(5).

Equations (13) can be also solved using Runge-Kutta fourth order method as previously explained in thermal wave model.

2.3. FitzHugh-Nagumo model

This model suggests that cardiac potential is governed by [18]:

$$\frac{\partial U}{\partial t} = D \frac{\partial^2 U}{\partial x^2} + \gamma U(a-U)(U-1), \quad t > 0, 0 < x < a, 0 < a < 1$$  \hspace{1cm} (14)

Where: $U(x,t)$ is the cardiac potential at position $x$ and time $t$, $\alpha$ represent the threshold for excitation, $D$ is the diffusion coefficient and $\gamma$ is rate parameter of reaction term.

Potential along external boundaries can be described as:

$$a_{ij}U(x_{i-1},0) + b_{ij} \frac{\partial U}{\partial x}(0,t) = f_1(t)$$  \quad (15-a)

$$a_{ij}U(x_j,t) + b_{ij} \frac{\partial U}{\partial x}(a,t) = f_2(t)$$  \quad (15-b)

Where $a_{ij}, b_{ij}$ and $f$, (i = 1, 2), are known functions.

The initial potential may be also described as:

$$U(x,0) = g(x)$$  \hspace{1cm} (16)

where $g(x)$ is a known function.

The method of differential quadrature can be applied to reduce Eqs. (14)-(16) to the following system of ODEs:

$$\frac{dU_j}{dt} = D \sum_{j=1}^{N} B_{ij}U_{(x_{j-1},0)} + \gamma (a-U_{(x_{j-1})})(U_{(x_{j-1})}-1)U_{(x_{j-1})}], i = 1,2,\ldots,N$$  \hspace{1cm} (17)

Where $B_{ij}$, (i, j = 1, N) is previously defined with thermal model.

Runge-Kutta method can be also employed to solve Eqs.(17) as in the previous models.

### 3. NUMERICAL RESULTS

To ensure the efficiency of the proposed technique (DQM + RK4), the three models are solved and compared with the available analytical solution [16,18]. Furthermore, a parametric study is introduced to investigate the effects of different reaction and diffusion parameters on the obtained results.

#### 3.1. Results for thermal wave propagation

Consider a one-dimensional problem of thermal wave propagation (along $x$-direction):

$$\alpha = a_1 = a_2 = U_0 = 1, \beta = a_3 = a_4 = b_1 = b_2 = b_3 = b_4 = f_1 = f_2 = 0$$

While $f_1(t) = \frac{1}{2}[1 + \tanh(2t)], f_2(t) = \frac{1}{2}[1 - \tanh(1 - 2t)]$

The exact solution for such problem can be obtained as [16]:

$$U_{exact}(x,t) = \frac{1}{2}(1 - \tanh(x - 2r)), \quad t > 0, 0 \leq x \leq 1$$

A one dimensional numerical scheme is designed with $\Delta t = 0.0005$ and $N = 5 \rightarrow 15$. To measure the errors of the obtained results, root mean square of errors are calculated such as [17].

Root mean square of errors $= RMS\ of\ errors = \sqrt{\frac{\sum_{i=1}^{NP}(U_{exact} - U)^2}{NP}}$

Where $U$ is the obtained approximate solution while $U_{exact}$ is the exact solution in [16]. $N$ is the number of nodes along $x$-direction while $P$ is the number of time steps.

Table 1 shows that (for $\Delta t = 0.0005$ and $N = 10$) the obtained results agree with the analytical ones [16] with $RMS\ of\ errors < 10^{-8}$. As well as, Fig. (1-a) shows that for different times and locations, the proposed technique leads to accurate results within absolute error $= |U - U_{exact}| \leq 1.4 \times 10^{-8}$.

<table>
<thead>
<tr>
<th>Time</th>
<th>5</th>
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Consider also a simple two dimensional problem with 
\( \alpha = \beta = a_1 = a_2 = a_3 = a_4 = 1, \)
\( \gamma = b_1 = b_2 = b_3 = f_1 = f_2 = f_3 = f_4 = 0 \) and 
\( g(x, y) = \sin \pi x \sin \pi y, 0 \leq x, y \leq 1 \)

This can be solved exactly as [19]; 
\[
U(x, y, t) = \sin \pi x \sin \pi y e^{-\gamma^2 t}
\]

The design of the numerical scheme is extended to two dimensions. Table 2 shows that for \( \Delta t = 0.00001, N = 8 \) and \( M = 7, \) the obtained results agree with the analytical ones [19] with \( R.M.S. \text{of errors} < 10^{-7}. \) Fig. (1-b) shows also (for two dimensional problems), that the proposed technique leads to accurate results with absolute error \( \|U - U_{exact}\| \leq 5 \times 10^{-6}. \)

### Table II

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<td>8.37143e-8</td>
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</table>

### 3.2. Results for Population density propagation model

In this example, it's assumed that:
\( a_1 = a_2 = U_0 = D = 1, b_1 = b_2 = 0. \) While
\[
f_1(t) = \frac{1}{[1 + \exp(-5\gamma t)]^2}, \quad f_2(t) = \frac{1}{[1 + \exp(\sqrt{\gamma^2 - 5\gamma t})]^{2}},
\]
\[
g(x) = \frac{1}{[1 + \exp(\sqrt{\gamma} x)]^2}, \quad 0 \leq x \leq 1.
\]
The exact solution for such problem can be obtained as [18]:

\[
U_{exact}(x, t) = \frac{1}{1 + \exp\left(\frac{\alpha}{6} x - 5 \gamma t / 6\right)}, \quad t > 0, 0 \leq x \leq 1
\]

Table III shows that (for \(\Delta t = 0.0005\) and \(N=10\)) the obtained results agree with the analytical ones [18] with \(R.M.S.\ of\ errors < 10^{-11}\). As well as, Fig. 3 shows that for different times and locations, the proposed technique leads to accurate results with absolute error \(\leq 10^{-10}\).

Table III

<table>
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<th>N</th>
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As well as a parametric study is introduced, through fig. 4, to investigate the influence of population density by the different values of reaction and diffusion parameters. For the prescribed boundary and initial conditions, the rate of reproduction is increased with increasing both of the values for \(\gamma\) and \(D\). Also, the computational instability is expected when \(D > 2.1\).

3.3 Results for cardiac potential model

In this example, it’s assumed that:

\[
a_1 = a_2 = U_0 = D = \gamma = 1, b_1 = b_2 = 0
\]

While:

\[
\begin{align*}
f_1(t) &= \frac{1}{2}(1 + \alpha) + \left(\frac{1}{2} - \frac{1}{2} \alpha\right) \tanh\left(\frac{(1 - \alpha^2)}{4} t\right), \\
f_2(t) &= \frac{1}{2}(1 + \alpha) + \left(\frac{1}{2} - \frac{1}{2} \alpha\right) \tanh\left(\frac{\sqrt{2}(1 - \alpha^2)}{4} t\right). \\
g(x) &= \frac{1}{2}(1 + \alpha) + \frac{1}{2}(1 - \alpha) \tanh\left(\frac{\sqrt{2}(1 - \alpha^2)}{4} x\right), \quad 0 \leq x \leq 1, 0 < \alpha < 1
\end{align*}
\]

The exact solution for such problem can be obtained as [18]:

\[
U_{exact}(x, t) = \frac{1}{2}(1 + \alpha) + \left(\frac{1}{2} - \frac{1}{2} \alpha\right) \tanh\left(\frac{\sqrt{2}(1 - \alpha^2)}{4} x\right), \quad t > 0, 0 \leq x \leq 1
\]

Table IV shows that (for \(\Delta t = 0.0005\) and \(N=10\)) the obtained results also agree with the analytical ones [18] with \(R.M.S.\ of\ errors < 10^{-15}\). As well as, Fig. 5 shows that for different times and locations, the proposed technique leads to accurate results within absolute error \(\leq 1.2 \times 10^{-14}\).

Table IV

<table>
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needs a small number of grid points and a little computational effort to obtain an accurate results with absolute error $\leq 5 \times 10^{-6}$. Furthermore, a parametric study is introduced to investigate the influence of reaction and diffusion characteristics on behavior of the obtained results.

**REFERENCES**


